## KNX EN

## KNX S4-B10 230 V KNX S2-B6 230 V KNX S1-B2 230 V

 Multifunctional ActuatorsTechnical Specifications and Installation Instructions

Item numbers 70530 (KNX S4-B10 230 V), 70531 (KNX S2-B6 230 V), 70532 (KNX S1-B2 230 V)


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## 1. Description

The Actuators KNX S4-B10, KNX S2-B6 and KNX S1-B2 230 V with integrated facade control have multifunctional outputs, pairs of buttons and monitoring LEDs. Each of the multifunctional outputs can connect to either a drive with Up/Down control (blinds, awnings, shutters, windows) or two switchable devices (On/Off for light and ventilation). The connected drives and devices can be operated directly on the actuator or via connected hand switches.

The automation can be specified externally or internally. Internally, there are numerous options available for blocking, locking (e.g. master-slave) and priority definition (e.g. manual-automatic). Scenes can be saved and called up via the bus (scene control with 16 scenes per drive).

Binary inputs can be used either for direct operation (e.g. hand switches) or as bus switches (or also for e.g. alarm notifications). The desired behaviour can be defined precisely through selection of the response times in Standard, Comfort or Deadman mode.

## Functions:

- Multifunctional outputs each for a 230 V drive (shade, window) or for connecting two switchable devices (light, fan) KNX S4-B10: 4 outputs | KNX S2-B6: 2 outputs | KNX S1-B2: 1 output
- Keypad with button pairs and status LEDs
- Binary inputs for use as hand switches or as bus switches with variable voltage ( $6 . . .80 \mathrm{~V}$ DC, $6 . . .240 \mathrm{~V}$ AC) KNX S4-B10: 10 inputs | KNX S2-B6: 6 inputs | KNX S1-B2: 2 inputs
- Automatic runtime measurement of the drives for positioning (including fault notification object)
- Position feedback (movement position, also slat position for blinds)
- Position storage (movement position) via 1-bit object (storage and call-up e.g. via button)
- Control via internal or external automation
- Integrated shade control for each drive output (with slat tracking according to sun position for blinds)
- Scene control for movement position with 16 scenes per drive (also slat position for blinds)
- Mutual locking of two drives using zero position sensors prevents collisions e.g. of shade and window (master-slave)
- Blocking objects and alarm notifications have different priorities, so safety functions always take precedence (e.g. wind block)
- Manual or automatic priority setting via time or communication object
- 5 Safety objects for each channel
- Short time restriction (movement command blocked) and movement limitation

Configuration is made using the KNX software ETS 5 . The product file can be downloaded from the Elsner Elektronik website on www.elsner-elektronik.de in the "Service" menu.

### 1.0.1. Scope of delivery

- Actuator


### 1.1. Technical Data

| Housing | Plastic |
| :--- | :--- |
| Colour | White |
| Assembly | Series installation on mounting rails |
| Protection Category | IP 20 |
| Ambient temperature | Operation $-20 \ldots+70^{\circ} \mathrm{C}$, Storage $-55 \ldots+90^{\circ} \mathrm{C}$ |
| Ambient humidity | max. $95 \% \mathrm{rH}$, avoid condensation |
| Operating voltage | $230 \mathrm{~V} \mathrm{AC}, 50 \mathrm{~Hz}$ |
| Current | on Bus: 10 mA |
| Minimum current for runtime meas- <br> urement | AC effective 200 mA |
| Max. cable length Binary inputs | 50 m |
| Data output | $\mathrm{KNX}+/-$ Bus connector terminal |
| BCU type | own microcontroller |
| PEl type | 0 |
| Goup addresses | max. 1024 |
| Assignments | max. 1024 |

## KNX S4-B10 230 V (No. 70530):

| Dimensions | approx. $107 \times 88 \times 60(\mathrm{~W} \times \mathrm{H} \times \mathrm{D}, \mathrm{mm}), 6$ dividing units |
| :--- | :--- |
| Weight | approx. 360 g |
| Power consumption | Operation max. approx. 3.5 W <br> Standby max. approx. 0.6 W |
| Outputs | $4 \times$ outputs each with 2 connections for drive up/down or 2 <br> devices, $230 \mathrm{~V}(\mathrm{PE} / \mathrm{N} / 1 / 2)$, <br> total. max 10 A and max. 4 A per connection |
| Inputs | $10 \times$ binary inputs, universal voltage <br> $(6 \ldots 80 \mathrm{~V}$ DC, $6 \ldots 240 \mathrm{~V} \mathrm{AC)}$ |
| Communication objects | 567 |

KNX S2-B6 230 V (No. 70531):

| Dimensions | approx. $107 \times 88 \times 60(\mathrm{~W} \times \mathrm{H} \times \mathrm{D}, \mathrm{mm}), 6$ dividing units |
| :--- | :--- |
| Weight | ca. 360 g |\(\left|\begin{array}{l}Operation max. approx, 3.5 \mathrm{~W} <br>


Standby max. ca. 0.6 \mathrm{~W}\end{array}\right|\)| $2 \times$ outputs |
| :--- |
| with 2 connections for drive Up/Down or 2 devices, |
| $230 \mathrm{~V}(\mathrm{PE} / \mathrm{N} / 1 / 2)$, |
| Power consumption |
| in total max. 10 A and max. 4 A per connection |


| Inputs | $6 \times$ binary inputs, universal voltage <br> $(6 \ldots 80 \mathrm{~V}$ DC, $6 \ldots 240 \mathrm{~V} \mathrm{AC})$ |
| :--- | :--- |
| Communication objects | 295 |

KNX S1-B2 230 V (No. 70532):

| Dimensions | approx. $53 \times 88 \times 60(\mathrm{~W} \times \mathrm{H} \times \mathrm{D}, \mathrm{mm}), 3$ dividing units |
| :--- | :--- |
| Weight | approx. 170 g |
| Power consumption | Operation max. approx, 1.2 W |
| Output | $1 \times$ Output with 2 connections for drive Up/Down or 2 <br> devices, $230 \mathrm{~V}(\mathrm{PE} / \mathrm{N} / 1 / 2)$, <br> in total max. 8 A and max. 4 A per connection |
| Inputs | $2 \times$ binary inputs, universal voltage <br> $(6 \ldots 80 \mathrm{~V}$ DC, $6 \ldots 240 \mathrm{~V} \mathrm{AC)}$ |
| Communication objects | 141 |

The products are compliant with the provisions of EU guidelines.

## 2. Installation and start-up

### 2.1. Installation notes

Installation, testing, operational start-up and troubleshooting should only be performed by an electrician.


## DANGER!

## Risk to life from live voltage (mains voltage)!

There are unprotected live components within the device.

- VDE regulations and national regulations are to be followed.
- Ensure that all lines to be assembled are free of voltage and take precautions against accidental switching on.
- Do not use the device if it is damaged.
- Take the device or system out of service and secure it against unintentional use, if it can be assumed, that risk-free operation is no longer guaranteed.

The device is only to be used for its intended purpose. Any improper modification or failure to follow the operating instructions voids any and all warranty and guarantee claims.

After unpacking the device, check it immediately for possible mechanical damage. If it has been damaged in transport, inform the supplier immediately.

The device may only be used as a fixed-site installation; that means only when assembled and after conclusion of all installation and operational start-up tasks and only in the surroundings designated for it.

Elsner Elektronik is not liable for any changes in norms and standards which may occur after publication of these operating instructions.

### 2.2. Connection

Follow the guidelines and standards for SELV electric circuits while installing and cable laying of the KNX connection and inputs.

## Binary inputs:

The connections of the binary inputs including the auxiliary voltage output meet the requirements for SELV electrical circuits. Mixed installation with non-SELV electrical circuits or mixing of different auxiliary voltages is not permitted.

### 2.2.1. Device Design KNX S4-B10 230 V

The device is designed for series installation on mounting rails and occupies 6 width units.


1) $-/ N($ bridged internally with terminal No. 5). When an external auxiliary voltage is used ( $6 . .80 \mathrm{~V}$ DC, $6 \ldots 240 \mathrm{~V} \mathrm{AC}$ ), one of the $-/ \mathrm{N}$ terminals is to be assigned with - or $N$
2) Free contacts (bridged internally)
3) Programmer LED and programmer buttons (PRG)
4) Bus terminal slot ( $K N X+$ +-)
5) $-/ N$ (bridged internally with terminal No. 1).
6) Binary inputs 1-6 (1 and 2: two bridged connections)
7) Internal auxiliary voltage +24 V DC. Only for binary inputs!

## Do not assign any external voltage!

8) Binary inputs 7-10
9) Up/Down button pairs and LEDs channel A-D
10) Power LED, Indication of operation mode. See "Indication of operation mode with the Power LED" on page 8.
11) Operating voltage input 230 V AC L/N/PE
12) Output A1-A2: "Up"-"Down" or "Device1"-"Device2", max. 4 A
13) Output B1 - B2: "Up"-"Down" or "Device1"-"Device2", max. 4 A
14) Output C1-C2: "Up"-"Down" or "Device1"-"Device2", max. 4 A
15) Output D1-D2: "Up"-"Down" or "Device1"-"Device2", max. 4 A
$\mathrm{N}^{\circ}$ 12-15
together
max. 10 A
16) All terminals $L, N, P E$ of the lower connection strip are bridged internally with "Main L, N, PE".

### 2.2.2. Device Design KNX S2-B6 230 V

The device is designed for series installation on mounting rails and occupies 6 width units.


1) $-/ N$ (bridged internally with terminal No. 5). When an external auxiliary voltage is used ( $6 . . .80$ V DC, $6 \ldots 240$ V AC), one of the -/N terminals is to be assigned with - or $N$
2) Free contacts (bridged internally)
3) Programming LED and programming buttons (PRG)
4) Bus terminal slot (KNX +/-)
5) -/N (bridged internally with terminals No. 1)
6) Binary inputs 1-2 (two bridged connections)
7) Internal auxiliary voltage +24 V DC. Only for binary inputs! Do not assign any external voltage!
8) Binary inputs 3-6
9) Up/Down button pairs and LEDs channel A-B
10) Mains LED (Power), mode status display. See "Indication of operation mode with the Power LED" on page 8.
11) Operating voltage input 230 V AC L/N/PE
12) Output A1-A2: "Up"-"Down" respectively "Device1"-"Device2", max. 4 A

No. 12-13 in total max. 10 A
13) Output B1 - B2: "Up"-"Down" respectively "Device1"-"Device2", max. 4 A
14) All terminals $L, N, P E$ of the lower connection strip are bridged internally with „main $L$, $N, P E^{\prime \prime}$.

### 2.2.3. Device Design KNX S1-B2 230 V

The device is designed for series installation on mounting rails and occupies 3 width units.


1) Programming LED and programming buttons (PRG)
2) Bus terminal slot ( $K N X+$ +-)
3) Switch pair Up/Down and LEDs
4) Mains LED (Power), mode status display. See "Indication of operation mode with the Power LED" on page 8.
5) Operating voltage input 230 V AC L/N/PE
6) Output A1-A2: "Up"-"Down" respectively "Device1"-"Device2", max. 4 A
7) All terminals $L, N, P E$ of the lower connection strip are bridged internally with „Main L, N, PE".
8) Binary inputs 1-2
9) Internal auxiliary voltage + 24 V DC. Only for binary inputs! Do not assign any external voltage!
10) -/N for external auxiliary voltage (6... 80 V DC, $6 \ldots 240$ V AC)
2.2.4. Indication of operation mode with the Power LED

| Behaviour | Colour |  |
| :--- | :--- | :--- |
| On | Green | Normal operation. <br> Bus connection/bus voltage available. |
| Flashes | Green | Normal operation. <br> No bus connection/bus voltage available. |
| On | Orange | Device starts up or is beeing programmed via the <br> ETS. <br> No automatic functions are executed. |
| Flashes | Green (on) <br> Orange <br> (flashing) | Programming mode active. |

### 2.2.5. Status display by the channel LEDs

| Behaviour | LED |  |
| :--- | :--- | :--- |
| To | top | Drive in top end position/device on. |
| To | bottom | Drive in bottom end position/drive on. |
| Flashes slowly | top | Drive moves up. |
| Flashes slowly | bottom | Drive moves down. |
| Flashes <br> quickly | top | Drive in top end position, blocking active. |
| Flashes <br> quickly | bottom | Drive in bottom position, blocking active. |
| Flashes <br> quickly | both <br> simultaneously | Drive in intermediate position, blocking active. |
| Extend | both | Drive in intermediate position. |
| Flashes | both alternately | Automatic runtime determination error. <br> If the drive can be moved, drive it into the end <br> position by hand (drive in/drive out <br> completely or open/close) in order to restart <br> the runtime determination. <br> If the drive cannot be moved, check the <br> connections. |
| "Runlight" <br> above all LEDs | all channels | Incorrect application version was loaded. Use <br> the version compatible with the device! |

### 2.3. Notes on mounting and commissioning

Device must not be exposed to water (rain). This could result in the electronic being damaged. A relative air humidity of $95 \%$ must not be exceeded. Avoid bedewing.

After the operating voltage has been applied, the device will enter an initialisation phase lasting a few seconds. During this phase no information can be received or sent via the bus.

For KNX devices with safety functions (e.g. wind or rain blocks), periodical monitoring of the safety objects must be set up. The optimal ratio is 1:3 (example: if the weather station sends a value every 5 minutes, the actuator must be configured for a monitoring period of 15 minutes).

### 2.4. Connection examples for binary inputs KNX S4-B10 and KNX S2-B6

### 2.4.1. Using the internal auxiliary voltage of the actuator

Other binary inputs corresponding.


### 2.4.2. Using an external voltage

B1 directly at the phase.
B3 via internally bridged voltage.
Other binary inputs corresponding.

External auxiliary voltage
6... 80 V DC resp. $6 . . .240$ V AC


### 2.5. Connecting example for binary inputs KNX S1-B2 230 V

### 2.5.1. Using the internal auxiliary voltage of the actuator



### 2.5.2. Using an external auxiliary voltage



